Give a suitable explanation of your answers!

The use of electronic devices is *not* allowed. A formula sheet is not handed out.

## Question 1.

(i) Compute the pivoted LU-decomposition of the matrix

$$\mathbf{A} = \begin{pmatrix} 0 & 3 & -2 \\ 4 & -2 & 1 \\ 2 & -1 & 1 \end{pmatrix}.$$

- (ii) Use the pivoted LU-decomposition calculated in (i) to compute the determinant of A.
- (iii) Use the pivoted LU-decomposition calculated in (i) to solve the linear system Ax = b with  $b = (6, -6, 0)^T$ .

Question 2. Let the linear system Ax = b be given by

$$\begin{pmatrix} 4 & a \\ a & 1 \end{pmatrix} \boldsymbol{x} = \begin{pmatrix} 4 \\ 1 \end{pmatrix}$$

with  $a \in \mathbb{R}$ .

- (i) Formulate the iteration procedure of the Jacobi method, and give the corresponding iteration matrix.
- (ii) For what values  $a \in \mathbb{R}$  does the Jacobi method converge?
- (iii) Choose a = 1 and consider the initial guess  $\mathbf{x}^{(0)} = (0,0)^T$ . Calculate two steps of the Jacobi method by hand and provide all calculation steps (i.e., stop whenever you calculated  $\mathbf{x}^{(2)}$ ).

## Question 3.

- (i) Compute an interpolating polynomial  $\Pi(x)$  through the points  $(x_i, y_i)$  with i = 0, 1, 2 for (0, 1), (1, 5) and (2, 3) using the Lagrange polynomials  $L_i(x)$ .
- (ii) Show that the interpolating polynomial is unique among all polynomials of degree less than or equal to two.
- (iii) Consider the perturbed point  $(x_1, \tilde{y}_1)$  with  $\tilde{y}_1 = 5 + \delta$ ,  $\delta \in \mathbb{R}$ , and denote  $\tilde{\Pi}(x)$  the corresponding interpolating through the points  $(x_0, y_0)$ ,  $(x_1, \tilde{y}_1)$  and  $(x_2, y_2)$ . Estimate the maximal error  $\Pi(x) \tilde{\Pi}(x)$  for  $x \in [0, 2]$ .

**Exercise 4.** For the approximation of  $\int_{-1}^{1} f(x)dx$  consider the quadrature formula

$$Q(f) = w_0 f(-\frac{1}{\sqrt{3}}) + w_1 f(\frac{1}{\sqrt{3}}).$$

- (i) Determine  $w_0$ ,  $w_1$  such that the degree of exactness is at least one.
- (ii) Determine the degree of exactness of Q(f).

Question 5. Let  $t_i = ih$  for h > 0 and  $i \in \mathbb{N}_0$ , and let  $f : \mathbb{R} \times \mathbb{R} \to \mathbb{R}$  be continuous and Lipschitz-continuous in the second argument. Consider the numerical method

$$y_{i+1} = y_i + hf(t_i + \frac{h}{2}, y_i + \frac{h}{2}f(t_i, y_i)), \qquad i \ge 0,$$
 (1)

for the approximation of the solution y(t) of the initial-value problem y'(t) = f(t, y(t)) for t > 0 and  $y(0) = y_0$ .

- (i) Show that (1) is a one-step method, i.e., specify the increment function.
- (ii) Show that the order of consistency of (1) is p=2. Hint: Taylor expansions in t+h/2.
- (iii) Show that (1) is zero-stable.
- (iv) Show that (1) is convergent and give the convergence order.

Question 6. We want to approximate the value of  $\pi$  by approximating the root  $x^* = \pi$  of  $\sin(x)$ . To that end, define  $M = \left[\frac{3\pi}{4}, \frac{5\pi}{4}\right]$ , and consider the fixed-point iteration

$$x_{k+1} = \phi(x_k), \quad \text{with } \phi(x) = x + \frac{\sin(x)}{2}.$$
 (2)

- (i) Show that  $\phi: M \to M$ , i.e.,  $\phi(x) \in M$  for all  $x \in M$ .
- (ii) Show that  $\phi: M \to M$  is a contraction.
- (iii) Show that the sequence  $\{x_k\}$  defined by (2) converges to  $\pi$ .
- (iv) Let  $\varepsilon > 0$ . Give a lower bound for k, such that  $|x_k \pi| < \varepsilon$ .

**Hint 1:** Consider  $\phi'(x)$ ,  $x \in M$ .

Hint 2: You may use that  $\cos(3\pi/4) = \cos(5\pi/4) = \sin(5\pi/4) = -1/\sqrt{2}$  and  $\sin(3\pi/4) = 1/\sqrt{2}$ .

Exercise	1.	2.	3.	4.	5.	6.	total	Grade
Points	2+2+2	2+2+1	2+2+2	2+2	1 + 3 + 2 + 1	2+2+2+2	36	(Points + 4)/4